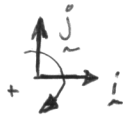
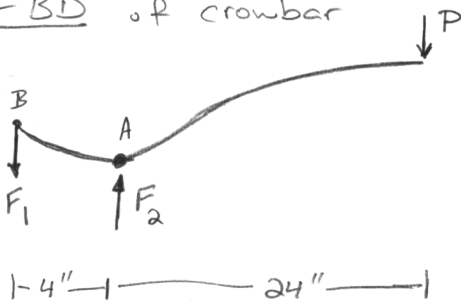


1

Find: Tension in the spike b such that the spike does not bend.



FBD of crowbar



from FBD of crowbar:

$$\sum \underline{F} \Rightarrow \{-F_1 \underline{j} + F_2 \underline{j} - P \underline{j} = 0\}$$

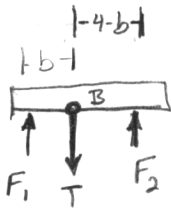
$$\{ \} \cdot \underline{j} \Rightarrow -F_1 + F_2 - P = 0 \quad (1)$$

$$\sum M_A \Rightarrow \{-4 \cdot F_1 \underline{k} + 24 P \underline{k} = 0\}$$

$$\{ \} \cdot \underline{k} \Rightarrow 4F_1 = 24P \Rightarrow \boxed{F_1 = 6P}$$

$$\boxed{F_1 = 180 \text{ lbf}}$$

FBD of board



using (1)

$$\boxed{F_2 = F_1 + P}$$

$$\boxed{F_2 = 210 \text{ lbf}}$$

from FBD of board:

$$\sum \underline{F} \Rightarrow \{F_1 \underline{j} + F_2 \underline{j} - T \underline{j} = 0\}$$

$$\{ \} \cdot \underline{j} \Rightarrow \boxed{T = F_1 + F_2}$$

$$\boxed{T = 390 \text{ lbf}}$$

To prevent bending

$$\sum M_B \Rightarrow \{b F_1 \underline{k} - (4-b) F_2 \underline{k} = 0\}$$

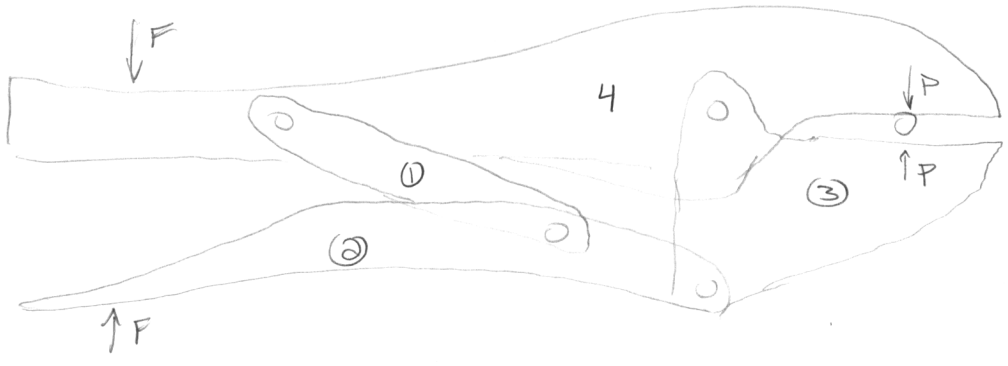
$$\{ \} \cdot \underline{k} \Rightarrow b F_1 = (4-b) F_2 = 0$$

$$b = \frac{4 F_2}{F_1 + F_2} = \frac{840}{390}$$

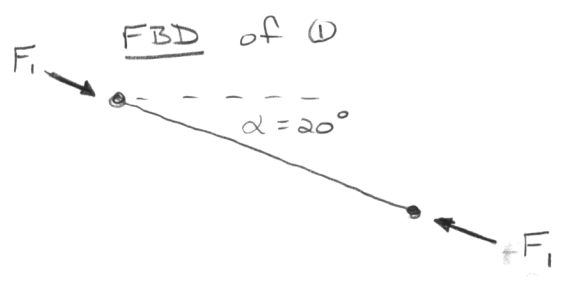
$$\boxed{b = 2.15 \text{ in}}$$

3

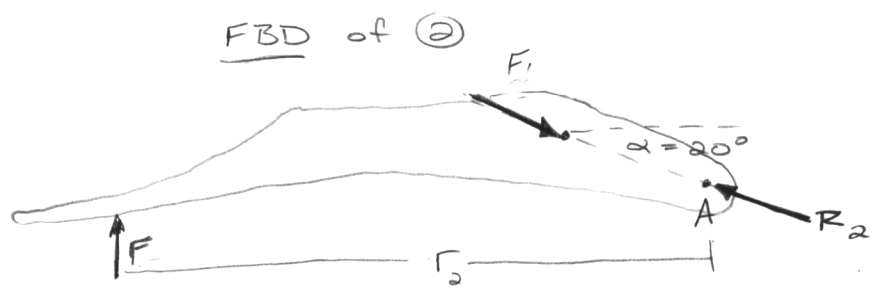
Find: Forces on each pin and member w/ $P=4000N$
 F to keep it clamped



Break wrench into components:



two force member: Forces equal and opposite



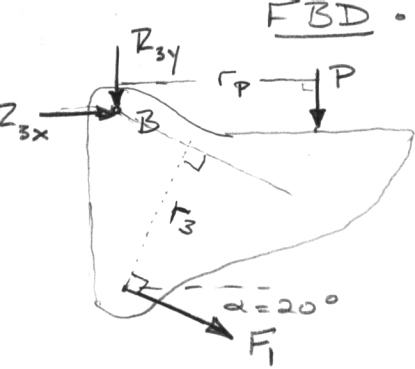
$$\sum M_A \Rightarrow r_2 F \underline{\hat{k}} = 0 \quad (F_1 \text{ acts through } A)$$

or $\boxed{F = 0}$

$$\sum \underline{F} \Rightarrow F_1 - R_2 = 0$$

$$\boxed{R_2 = F_1}$$

FBD - A3



3/7

$$\sum M_B \Rightarrow \{ r_P P \underline{k} - r_3 F_1 \underline{k} = 0 \}$$

$$\{ \} \cdot \underline{k} \Rightarrow r_P P = r_3 F_1$$

$$F_1 = \frac{r_P}{r_3} P$$

from drawing!

$$r_P = 2.6 \text{ cm}$$

$$r_3 = 2.175 \text{ cm}$$

so: $F_1 = 4781.61 \text{ N}$

$$\sum \underline{F} \cdot \underline{i} \Rightarrow \cos \alpha F_1 + R_{3x} = 0$$

$$R_{3x} = -4493.24 \text{ KN}$$

$$\sum \underline{F} \cdot \underline{j} \Rightarrow -\sin \alpha F_1 - P - R_{3y} = 0$$

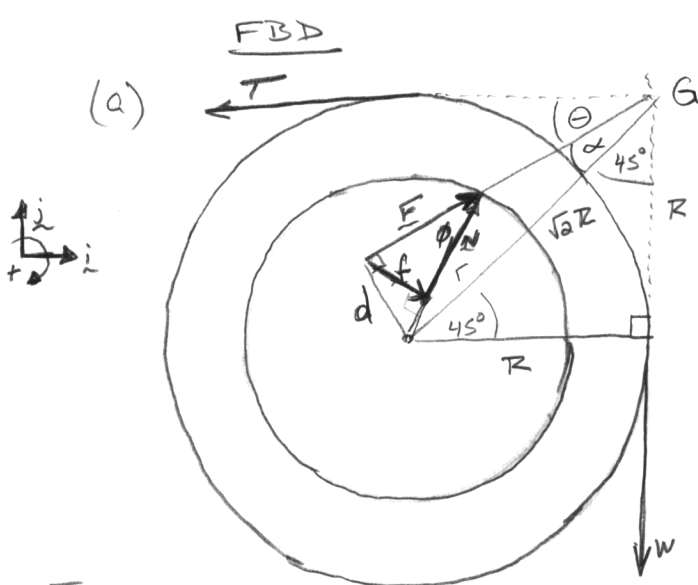
$$R_{3y} = -5635.41 \text{ N}$$

Forces R_{3x} and R_{3y} act in the opposite direction on member ④

Note: Your answers may be slightly different due to differences in measuring, however $F=0$ for any measurement.

4 Find: T when (a) weight moves up at steady speed
(b) weight moves down at steady speed

Given: $w = 100 \text{ lb}$ $r = 0.2 \text{ in}$ $R = 2 \text{ in}$ $\mu = 0.3$
unlubricated bearing
axle cannot rotate
pulley fits loosely on axle



$$\vec{F} = \vec{f} + \vec{N} \quad (1)$$

The lines of the 3 forces (T, w, F) intersect at a single point and are coplanar ("3 Force Body")

$$\tan \phi = \mu \quad (2)$$

$$d = r \sin \phi \quad (3)$$

$$\sin \alpha = \frac{d}{\sqrt{2} R} \quad (4)$$

Combining (3) and (4) and solving for α :

$$\alpha = \sin^{-1} \left(\frac{r \sin \phi}{\sqrt{2} R} \right) \quad (5)$$

$$\Theta = \frac{\pi}{2} - \left(\alpha + \frac{\pi}{4} \right) = \frac{\pi}{4} - \alpha \quad (6)$$

Combining (5) and (6):

$$\Theta = \frac{\pi}{4} - \sin^{-1} \left(\frac{r \sin \phi}{\sqrt{2} R} \right) \quad (7)$$

$$\sum \underline{F} \Rightarrow \{-T \underline{i} + W \underline{j} + F \cos \theta \underline{i} + F \sin \theta \underline{j} = \underline{0}\}$$

$$\{ \} \cdot \underline{i} \Rightarrow -T + F \cos \theta = 0 \quad (8)$$

$$\{ \} \cdot \underline{j} \Rightarrow -W + F \sin \theta = 0 \quad (9)$$

$$\text{From (9): } F = \frac{W}{\sin \theta} \quad (10)$$

Subs. (10) into (8):

$$T = \frac{W}{\sin \theta} \cos \theta = \frac{W}{\tan \theta}$$

$$T = \frac{W}{\tan \left[\frac{\pi}{4} - \sin^{-1} \left(\frac{r \sin \phi}{\sqrt{2} R} \right) \right]}$$

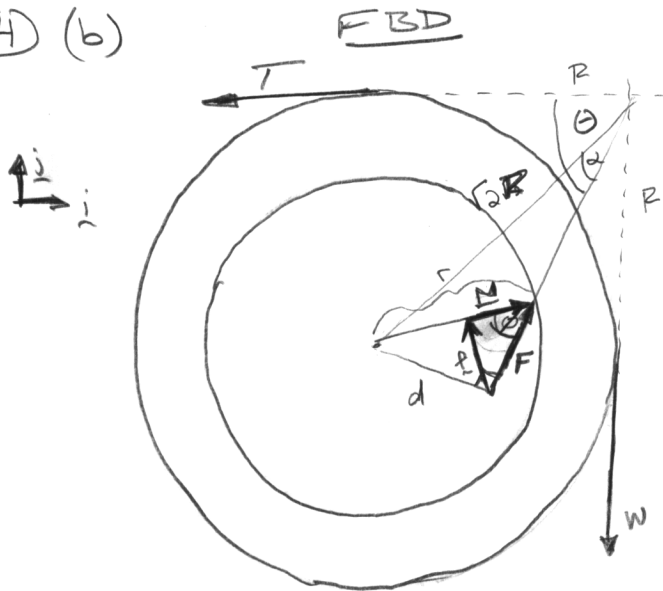
$$\boxed{T = 104.15 \text{ lbf}}$$

Note: if $\mu \rightarrow \infty$ then $\phi = \frac{\pi}{2}$ and $\sin \phi = 1$

$$\text{SO } T = \frac{W}{\tan \left[\frac{\pi}{4} - \sin^{-1} \left(\frac{r}{\sqrt{2} R} \right) \right]} = 115.26 \text{ lbf}$$

for ∞ friction !!

④ (b)



as in part (a)

$$\underline{F} = \underline{f} + \underline{N}$$

$$\tan \phi = \mu$$

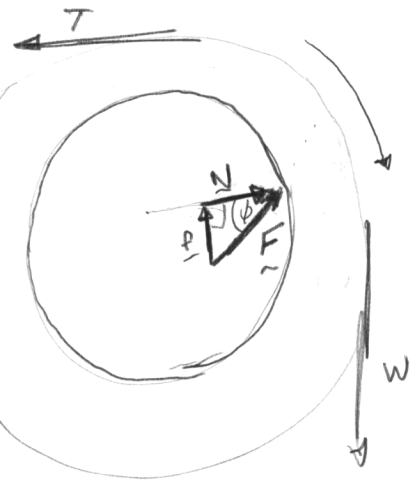
$$d = r \sin \phi$$

$$\alpha = \sin^{-1} \left(\frac{r \sin \phi}{\sqrt{2} R} \right)$$

$$\Theta = \frac{\pi}{4} + \alpha \quad (11)$$

Subs. α ;

$$\Theta = \frac{\pi}{4} + \sin^{-1} \left(\frac{r \sin \phi}{\sqrt{2} R} \right)$$



$$\sum \underline{F} \Rightarrow \left\{ -T \underline{i} - W \underline{j} + F \cos \Theta \underline{i} + F \sin \Theta \underline{j} = \underline{0} \right\}$$

→ same as (a) so:

$$T = \frac{W}{\tan \Theta} = \frac{W}{\tan \left[\frac{\pi}{4} + \sin^{-1} \left(\frac{r \sin \phi}{\sqrt{2} R} \right) \right]}$$

$$\boxed{T = 96.02 \text{ lbf}}$$

Note: if $\mu \rightarrow \infty$ $\phi = \frac{\pi}{2}$ $\sin \phi = 1$ then $T = 86.76 \text{ lbf}$

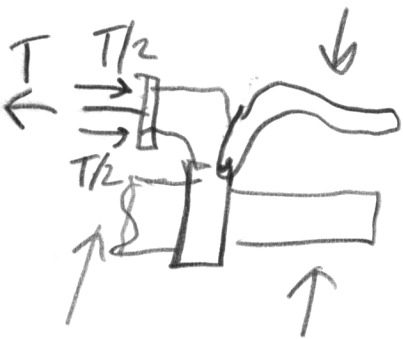
Problems w/ example:

① F_{b1} does not necessarily equal F_{b2} . In the case of a rider seated on the bike at a standstill it may, but deceleration would cause additional force to be placed on the handlebar so $F_{b1} > F_{b2}$

② When the cable was cut for the FBD a force was added from the cable, but none from the cable housing. The cable housing is in compression.

handle
FBD
(pg 109)
should
look like
this


In fact, if you assume that the cable and housing have no bending strength/stiffness \Rightarrow net cable+housing tension = 0 \Rightarrow housing compression = cable tension.



Look at FBD of curved piece of cable & housing



Now cut at A-A

\Rightarrow  \Rightarrow no equilb. unless forces are zero
 \Rightarrow no net tension in housing/cable combo.

No forces
or couples
here!

(they turn
out to be zero)