

6.5.1 Define these terms

- a) statically determinate
- b) rigid and non-rigid
- c) redundant and non-redundant

a) A truss that yields a single unique solution is a statically determinate truss.

b) A non-rigid truss is one that cannot carry arbitrary loads at its joints.

c) A redundant truss is one that contains more unknown tensions than equations which can be derived.

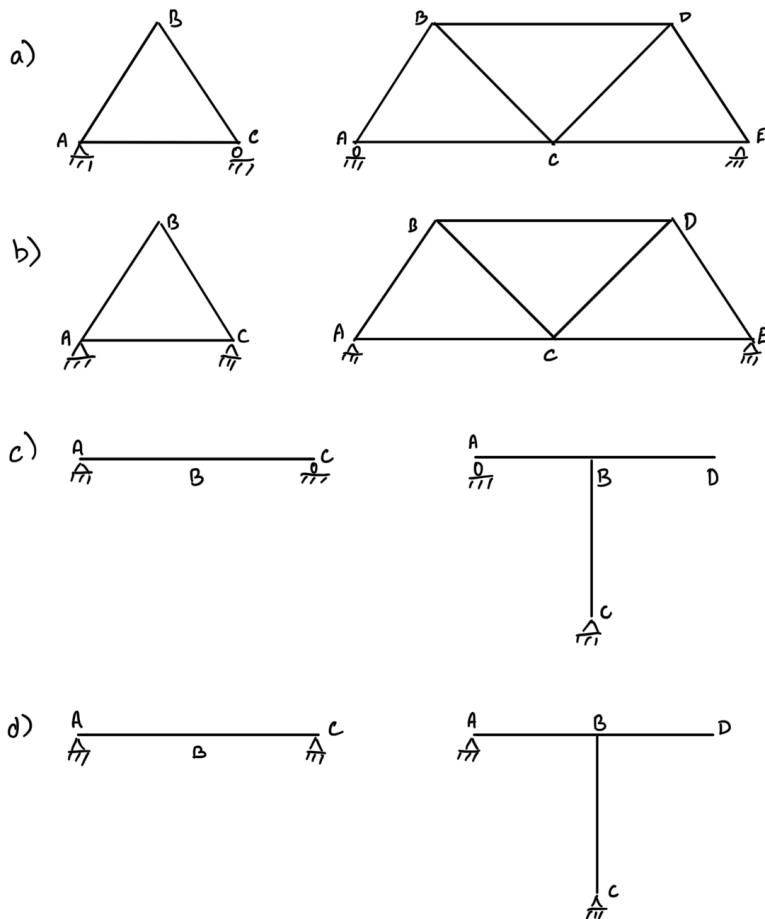
6.5.2 For each set of conditions below, find 2 trusses both of which fit the description

a) rigid and non-redundant

b) rigid and redundant

c) not rigid and not redundant

d) not rigid and redundant



Disclaimer: We have lost track of the many people who wrote these solutions. They are not official and have not been reviewed by the authors for correctness.

6.5.3 In 2D trusses we used the formula $b + r = 2j$. With what formula do we replace this for 3D trusses? Explain why.

$$3j = b + r$$

The number of unknowns = no. of bars + no. of reactions

This is because the truss is a two-force body

The number of equations = 3 x no. of joints

There will be 3 force balance equations at the joint.

Hence the formula for a 3-D truss is :

$$3j = b + r$$

6.5.4 For the 3D method of joints, for a whole truss how many independent scalar equilibrium equations can one write?

At each joint of a 3-D truss, 3 scalar force-balance equations can be applied:

$$\sum F_x = 0$$

$$\sum F_y = 0$$

$$\sum F_z = 0$$

6.5.5 For one section cut in 3D how many bar tensions can you hope to find?

From one section of a 3-D truss 6 scalar balance equations are obtained:

$$\sum F_x = 0$$

$$\sum F_y = 0$$

$$\sum F_z = 0$$

$$\sum \vec{M}_{hx} = \vec{0}$$

$$\sum \vec{M}_{hy} = \vec{0}$$

$$\sum \vec{M}_{hz} = \vec{0}$$

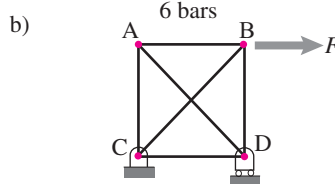
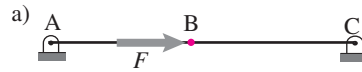
Hence, 6 tensions can be found from a single section of a 3-D Truss.

6.5.6 For a 3D truss that is rigid when not grounded, how many independent reaction components do you need to make it a statically determinate structure for any loading?

For a 3-D truss, 6 reaction components are required to make it statically determinate.

6.5.7 For the following structures find at least 2 different sets of bar forces that can equilibrate the applied load shown.

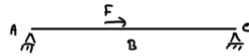
- a) Two bars in a line with a force in the same line.
 b) A square with two diagonal braces.



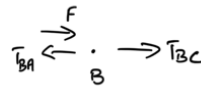
Problem 6.7

a)

Sketch:



FBD (Joint):



$$\sum F_x = 0$$

$$\Rightarrow T_{BC} + T_{BA} + F = 0$$

$$\Rightarrow T_{BC} + T_{BA} = -F$$

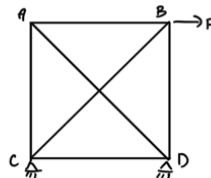
$$\Rightarrow T_{BC} = -\frac{1}{3}F, T_{BA} = -\frac{2}{3}F$$

or

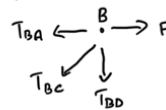
$$T_{BC} = -\frac{1}{3}F, T_{BA} = \frac{1}{3}F$$

b)

Sketch:



FBD (Joint):



$$\sum F_x = T_{BA} - T_{BC} \cos 45^\circ + F = 0$$

$$\Rightarrow T_{BA} - T_{BC} \cos 45^\circ = -F$$

$$\Rightarrow T_{BA} = T_{BC} \cos 45^\circ - F$$

$$\sum F_y = -T_{BC} \sin 45^\circ - T_{BD} = 0$$

$$\Rightarrow T_{BD} = -T_{BC} \sin 45^\circ$$

$$\sum F_x = T_{AB} + T_{AD} \cos 45^\circ = 0$$

$$\Rightarrow -T_{BA} + T_{AD} \cos 45^\circ = 0$$

$$\Rightarrow T_{AD} = T_{BA}$$

$$= T_{BC} - F \sec 45^\circ$$

$$\sum F_y = -T_{AD} \sin 45^\circ - T_{AC} = 0$$

$$\Rightarrow T_{AC} = -T_{AD} \sin 45^\circ$$

$$= -T_{BC} \sin 45^\circ + F \tan 45^\circ$$

$$\sum F_x = D_x - T_{DC} - T_{DA} \cos 45^\circ = 0$$

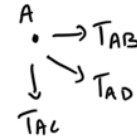
$$\Rightarrow D_x - T_{DC} = T_{DA} \cos 45^\circ$$

$$\Rightarrow D_x - T_{DC} = F - T_{BC} \cos 45^\circ \quad (i)$$

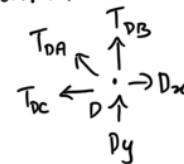
$$\sum F_y = D_y + T_{DB} + T_{DA} \sin 45^\circ = 0$$

$$\Rightarrow D_y + T_{DB} = F \tan 45^\circ - T_{BC} \sin 45^\circ$$

FBD (Joint):



FBD (Joint):



$$\Rightarrow D_y = F \tan 45^\circ - 2T_{BC} \sin 45^\circ$$

$$\sum F_x = C_x + T_{CD} + T_{CB} \cos 45^\circ = 0$$

$$\Rightarrow C_x + T_{CD} = T_{BC} \cos 45^\circ \quad - (ii)$$

$$\sum F_x = C_x + D_x = F$$

$$\Rightarrow D_x = F - C_x$$

Substitute in (i)

$$F - C_x - T_{DC} = F - T_{BC} \cos 45^\circ \quad - (iii)$$

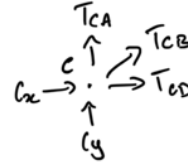
$$C_x - T_{DC} = T_{BC} \cos 45^\circ \quad - (iv)$$

$$(iii) + (iv)$$

$$F - 2T_{DC} = F$$

$$T_{DC} = 0$$

FBD (Joint):



FBD (Whole Structure):

