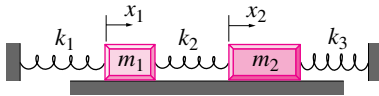


11.3 Normal Modes

11.3.1 A two degree of freedom mass-spring system, made up of two unequal masses m_1 and m_2 and three springs with unequal stiffnesses k_1 , k_2 and k_3 , is shown in the figure. All three springs are relaxed in the configuration shown. Neglect friction.

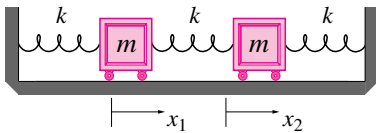
- Derive the equations of motion for the two masses.
- Does each mass undergo simple harmonic motion? *



Problem 11.3.1

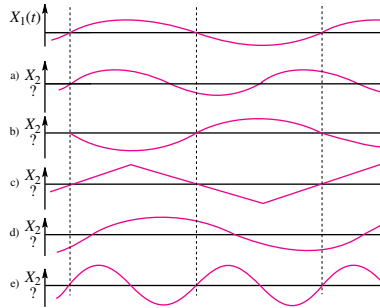
11.3.2 Normal Modes. Three equal springs (k) hold two equal masses (m) in place. There is no friction. x_1 and x_2 are the displacements of the masses from their equilibrium positions.

- How many independent normal modes of vibration are there for this system? *
- Assume the system is in a normal mode of vibration and it is observed that $x_1 = A \sin(ct) + B \cos(ct)$ where A , B , and c are constants. What is $x_2(t)$? (The answer is not unique. You may express your answer in terms of any of A , B , c , m and k .) *
- Find all of the frequencies of normal-mode-vibration for this system in terms of m and k . *



Problem 11.3.2

11.3.3 $x_1(t)$ and $x_2(t)$ are measured positions on two points of a vibrating structure. $x_1(t)$ is shown. Some candidates for $x_2(t)$ are shown. Which of the $x_2(t)$ could possibly be associated with a normal mode vibration of the structure? Answer “could” or “could not” next to each choice and briefly explain your answer (If a curve looks like it is meant to be a sine/cosine curve, it is.)

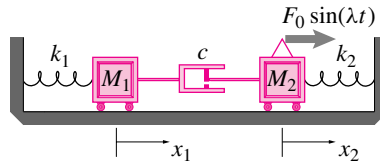


Problem 11.3.3

More-Involved Problems

11.3.4 Two masses are connected to fixed supports and each other with the two springs and dashpot shown. The displacements x_1 and x_2 are defined so that $x_1 = x_2 = 0$ when both springs are unstretched.

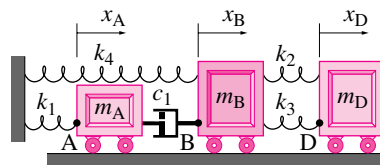
For the special case that $C = 0$ and $F_0 = 0$ clearly define two different sets of initial conditions that lead to normal mode vibrations of this system.



Problem 11.3.4

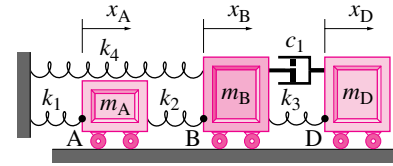
11.3.5 As in problem 10.4.11, a system of three masses, four springs, and one damper are connected as shown. Assume that all the springs are relaxed when $x_A = x_B = x_D = 0$.

- In the special case when $k_1 = k_2 = k_3 = k_4 = k$, $c_1 = 0$, and $m_A = m_B = m_D = m$, find a normal mode of vibration. Define it in any clear way and explain or show why it is a normal mode in any clear way. *
- In the same special case as in (a) above, find another normal mode of vibration. *



Problem 11.3.5

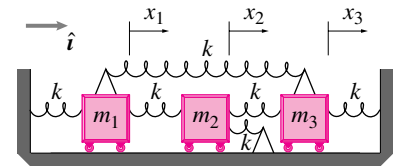
11.3.6 As in problem 10.4.10, a system of three masses, four springs, and one damper are connected as shown. In the special case when $c_1 = 0$, find the normal modes of vibration.



Problem 11.3.6

11.3.7 Normal modes. All three masses have $m = 1$ kg and all 6 springs are $k = 1$ N/m. The system is at rest when $x_1 = x_2 = x_3 = 0$.

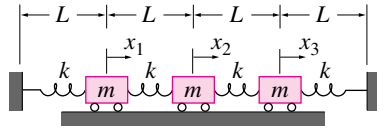
- Find as many different initial conditions as you can for which normal mode vibrations result. In each case, find the associated natural frequency. (we will call two initial conditions $[v]$ and $[w]$ different if there is no constant c so that $[v_1 \ v_2 \ v_3] = c[w_1 \ w_2 \ w_3]$. Assume the initial velocities are zero.)
- For the initial condition $[x_0] = [0.1 \text{ m} \ 0 \ 0]$, $[\dot{x}_0] = [0 \ 2 \text{ m/s} \ 0]$ what is the initial (immediately after the start) acceleration of mass 2?



Problem 11.3.7

11.3.8 For the three-mass system shown, assume $x_1 = x_2 = x_3 = 0$ when all the springs are fully relaxed. One of the normal modes is described with the initial condition $(x_{10}, x_{20}, x_{30}) = (1, 0, -1)$.

- What is the angular frequency ω for this mode? Answer in terms of L , m , k , and g . (Hint: Note that in this mode of vibration the middle mass does not move.) *
- Make a neat plot of x_3 versus x_1 for one cycle of vibration with this mode.
- Make a single plot with both x_1 and x_3 vs t for one cycle of this mode.



Problem 11.3.8